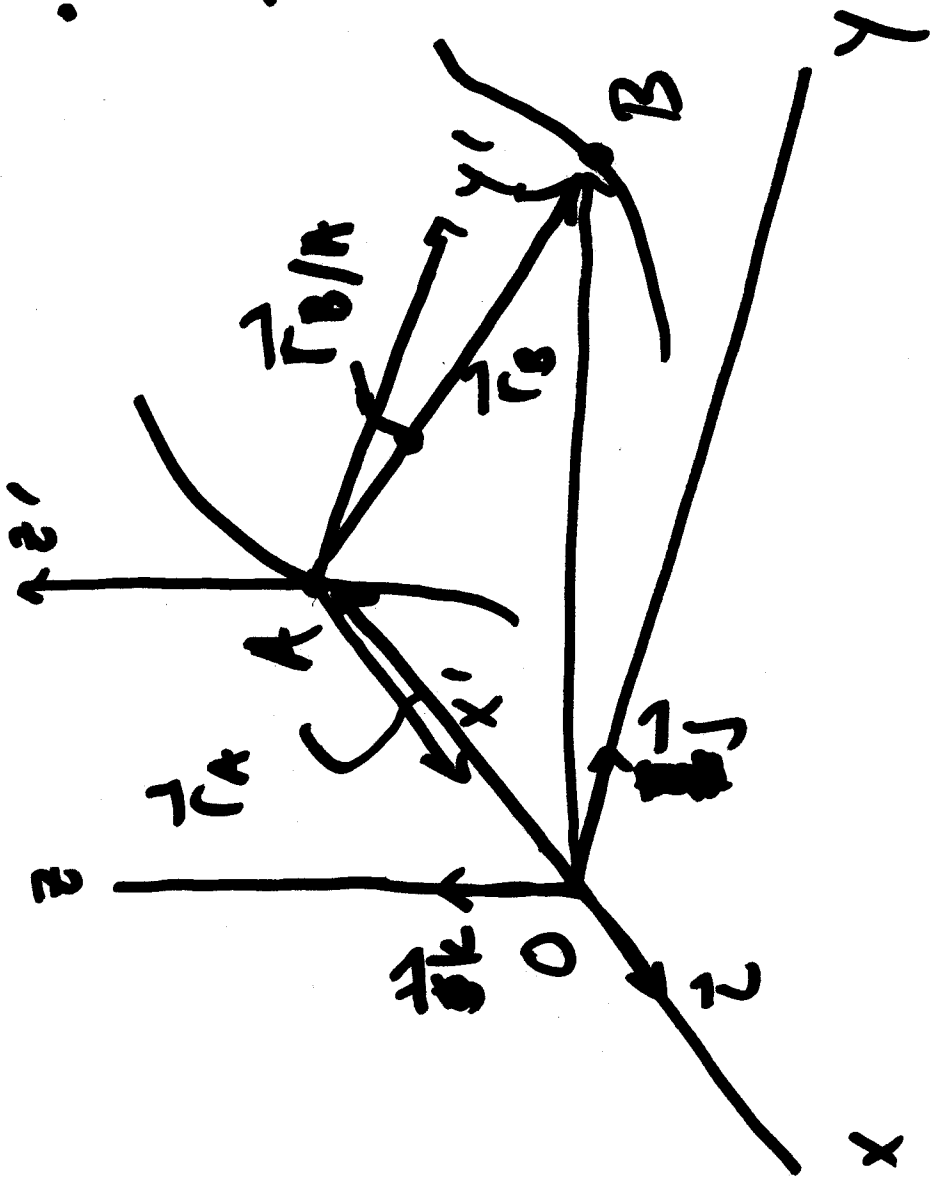
 University of Idaho Section 12.9 Absolute

Dependent Motion Analysis of Two Particles

⇒ Motion of one particle directly determines the motion of other particles.

⇒ Pulley problems

University of Idaho Section 12.10 Relative Motion of Two Particles Using Translating Axes



• XYZ fixed in

Space  
 •  $\vec{i}, \vec{j}, \vec{k}$  attached to XYZ

• From  $x'y'z''$  attached to particle A

•  $x'y'z'' \parallel xyz$

$x'y'z''$  translates  
 but does not rotate

UNIVERSITY OF IDAHO •  $\vec{z}'$ ,  $\vec{y}'$ ,  $\vec{k}'$  to the system  $x'y'z'$

• Because  $x'y'z'$  translates, but does not rotate

$$\vec{z}' = \vec{z}, \vec{y}' = \vec{y}, \vec{k}' = \vec{k}$$

$$\vec{r}'_A = x_A \vec{z} + y_A \vec{y} + z_A \vec{k} \quad \left. \begin{array}{l} \text{Position of A : B} \\ \text{relative to the fixed frame} \end{array} \right\}$$

$$\vec{r}'_B = x_B \vec{z} + y_B \vec{y} + z_B \vec{k} \quad \left. \begin{array}{l} \\ \text{xyze} \end{array} \right\}$$

$$\begin{aligned} \vec{r}'_{B/A} &= x'_{B/A} \vec{z}' + y'_{B/A} \vec{y}' + z'_{B/A} \vec{k}' \quad \left. \begin{array}{l} \text{Position of} \\ \text{B as it appears} \\ \text{from A} \end{array} \right\} \\ &= x'_{B/A} \vec{z} + y'_{B/A} \vec{y} + z'_{B/A} \vec{k} \end{aligned}$$

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University of Idaho Supposing that we know two of the three  $\vec{r}_A$ ,  $\vec{r}_B$ ,  $\vec{r}_{BA}$ , and wish to calculate the other, we can use the vector triangle equation

$$\vec{r}_B = \vec{r}_A + \vec{r}_{B/A}$$

We can easily change, place the  $x'y'z'$  system on B, and get

$$\vec{r}_A = \vec{r}_B + \vec{r}_{A/B}$$

UNIVERSITY OF IDAHO We can extend to relative velocity

by taking the time derivative:

$$\frac{d\vec{r}_B}{dt} = \frac{d\vec{r}_A}{dt} + \frac{d\vec{r}_{B/A}}{dt} \Rightarrow \boxed{\vec{v}_B = \vec{v}_A + \vec{v}_{B/A}}$$

}

$$\frac{d\vec{r}_B}{dt} = \frac{d}{dt}(x_B \hat{i}) + \frac{d}{dt}(y_B \hat{j}) + \frac{d}{dt}(z_B \hat{k})$$

$$= \dot{x}_B \hat{i} + \dot{y}_B \hat{j} + \dot{z}_B \hat{k}$$

$$\dot{x}_B \vec{i} + \dot{y}_B \vec{j} + \dot{z}_B \vec{k} = \dot{x}_A \vec{i} + \dot{y}_A \vec{j} + \dot{z}_A \vec{k} \\ + \dot{x}'_{B/A} \vec{i} + \dot{y}'_{B/A} \vec{j} + \dot{z}'_{B/A} \vec{k}$$

And, we can further extend to acceleration by taking the time derivative

~~$$\frac{d\vec{v}_A}{dt} = \frac{d\vec{v}_B}{dt} + \frac{d\vec{v}_{B/A}}{dt} \Rightarrow \vec{a}_A = \vec{a}_B$$~~

$$\frac{d\vec{v}_B}{dt} = \frac{d\vec{v}_A}{dt} + \frac{d\vec{v}_{B/A}}{dt} \Rightarrow \boxed{\vec{a}_B = \vec{a}_A + \vec{a}_{B/A}}$$