

Section 13.5 Equations of Motion: Normal and

Tangential Coordinates

$$\vec{F} = m\vec{a} \quad \text{2D problems}$$

$$\vec{a} = a_t \vec{u}_t + a_n \vec{u}_n = \dot{v} \vec{u}_t + v \frac{v^2}{\rho} \vec{u}_n$$

$$\vec{F} = F_n \vec{u}_n + F_t \vec{u}_t$$

$$F_n \vec{u}_n + F_t \vec{u}_t = m \left(\dot{v} \vec{u}_t + \frac{v^2}{\rho} \vec{u}_n \right)$$

9/2

UNIVERSITY OF IDAHO We'll end up with the two scalar

Equations

$$F_t = m\dot{v} \quad \varepsilon \quad F_n = m \frac{v^2}{\rho}$$

If we have forces in the vertical direction, then we would have a third scalar equation.

Section 13.6 Equations of Motion: Cylindrical Coordinates

$$\begin{aligned} \vec{a} &= a_r \vec{u}_r + a_\theta \vec{u}_\theta + a_z \vec{u}_z \\ &= (\ddot{r} - r\dot{\theta}^2) \vec{u}_r + (2\dot{r}\dot{\theta} + r\ddot{\theta}) \vec{u}_\theta + \ddot{z} \vec{u}_z \end{aligned}$$

UNIVERSITY OF IDAHO The vector sum of applied external forces \vec{F} will be decomposed into components along the

$\hat{u}_r, \hat{u}_\theta$: \hat{u}_z directions:

$$\vec{F} = F_r \hat{u}_r + F_\theta \hat{u}_\theta + F_z \hat{u}_z$$

Equating coefficients of unit vectors;

$$F_r = m(\ddot{r} - r\dot{\theta}^2)$$

$$F_\theta = m(r\ddot{\theta} + 2\dot{r}\dot{\theta})$$

$$F_z = m\ddot{z}$$