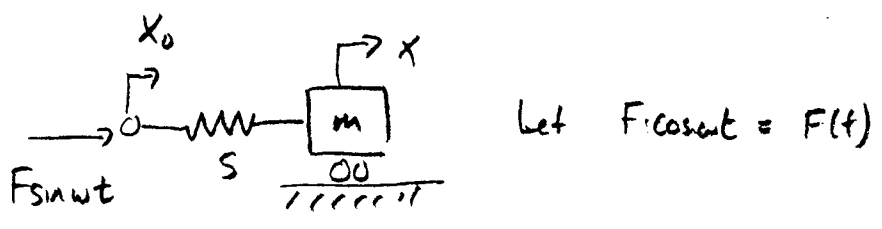


1.12.1



without loss in generality, change $\sin wt \rightarrow \cos wt$

EOM's are $F(t) - s(x_0 - x) = 0$

$$-s(x - x_0) = m\ddot{x}$$

EOM for driven end is (eliminate x)

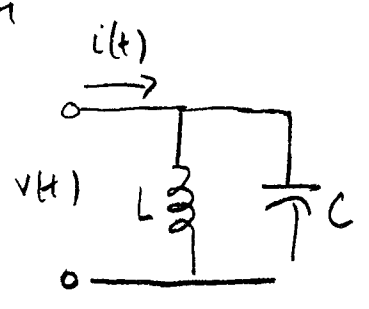
$$F(t) - s x_0 = -s x \quad x = -\frac{1}{s} F(t) + x_0$$

$$\ddot{x} = -\frac{1}{s} \ddot{F}(t) + \ddot{x}_0$$

So
$$-s\left(-\frac{1}{s} F(t) + x_0 - x_0\right) = -\frac{m}{s} \ddot{F}(t) + m \ddot{x}_0$$

$$F(t) + \frac{m}{s} \ddot{F}(t) = m \ddot{x}_0 = m \dot{v}_0$$

$v_0 = \dot{x}$ = speed of driven end



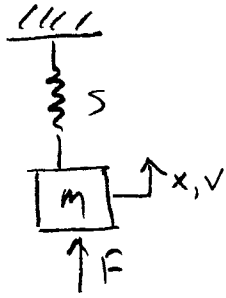
$$i(t) = \frac{1}{L} \int v dt + c \frac{dv}{dt}$$

$$\frac{di}{dt} = \frac{1}{L} v + c \frac{d^2 v}{dt^2}$$

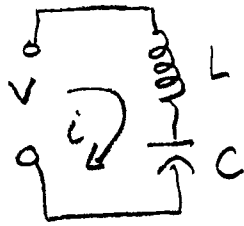
$$L \frac{di}{dt} = v + LC \frac{d^2 v}{dt^2}$$

these two are identical

a.

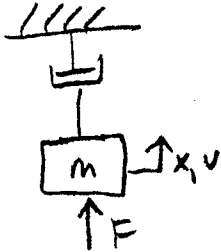


$$F = m\ddot{x} + sx = m\dot{v} + s \int v dt$$

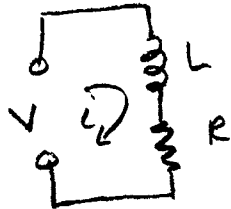


$$V = L \frac{di}{dt} + \frac{1}{C} \int i dt$$

b.

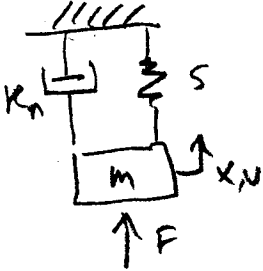


$$F = m\ddot{x} + R_m \dot{x} = m\dot{v} + R_m v$$

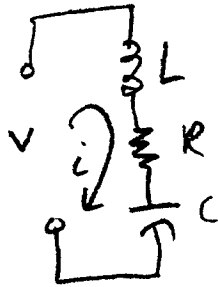


$$V = L \frac{di}{dt} + R i$$

c.



$$F = m\ddot{x} + R_m \dot{x} + sx = m\dot{v} + R_m v + s \int v dt$$



$$V = L \frac{di}{dt} + R i + \frac{1}{C} \int i dt$$